

# EVS SERIES Right-angle Planetary

## EVS o6o 2-Stage Specifications

Frame Size	060									
Ratio	Unit	Note	3	4	5	6	7	8	9	10
Nominal Output Torque	[Nm]	*1	12	16	22	24	24	24	19	19
Maximum Acceleration Torque	[Nm]	*2	29	38	48	54	54	54	38	38
Maximum Torque	[Nm]	*3	33	45	56	63	63	61	45	45
Emergency Stop Torque	[Nm]	*4	50	65	80	90	90	90	65	65
Nominal Input Speed	[rpm]	*5				3300				
Maximum Input Speed	[rpm]	*6				6000				
No Load Running Torque	[Nm]	*7				0.33				
Maximum Radial Load	[N]	*8				3000				
Maximum Axial Load	[N]	*9				2700				
Moment of Inertia ( $\leq \emptyset 8$ )	[kgcm <sup>2</sup> ]	--	0.320	0.271	0.251	0.242	0.235	0.232	0.229	0.228
Moment of Inertia ( $\leq \emptyset 14$ )	[kgcm <sup>2</sup> ]	--	0.395	0.346	0.326	0.317	0.310	0.307	0.304	0.303
Moment of Inertia ( $\leq \emptyset 19$ )	[kgcm <sup>2</sup> ]	--	0.584	0.535	0.516	0.506	0.500	0.496	0.494	0.492
Efficiency	[%]	*10				93				
Torsional Rigidity	[Nm/arc-min]	*11				3				
Maximum Torsional Backlash	[arc-min]	--				$\leq 4$				
Noise Level	dB [A]	*12				$\leq 80$				
Protection Class	--	*13				IP54 (IP65)				
Ambient Temperature	[°C]	--				0-40				
Permitted Housing Temperature	[°C]	--				90				
Weight	[kg]	*14				2.0				

## EVS o6o 3-Stage Specifications

Frame Size	060									
Ratio	Unit	Note	15	16	20	25	28	30	35	40
Nominal Output Torque	[Nm]	*1	18	26	26	28	28	19	28	28
Maximum Acceleration Torque	[Nm]	*2	38	54	54	54	54	38	54	54
Maximum Torque	[Nm]	*3	38	54	54	54	54	38	54	54
Emergency Stop Torque	[Nm]	*4	65	90	90	90	90	65	90	90
Nominal Input Speed	[rpm]	*5				3800				
Maximum Input Speed	[rpm]	*6				6000				
No Load Running Torque	[Nm]	*7				0.20				
Maximum Radial Load	[N]	*8				3000				
Maximum Axial Load	[N]	*9				2700				
Moment of Inertia ( $\leq \emptyset 8$ )	[kgcm <sup>2</sup> ]	--	0.074	0.079	0.072	0.071	0.077	0.062	0.070	0.061
Moment of Inertia ( $\leq \emptyset 14$ )	[kgcm <sup>2</sup> ]	--	0.118	0.124	0.116	0.115	0.122	0.106	0.115	0.106
Moment of Inertia ( $\leq \emptyset 19$ )	[kgcm <sup>2</sup> ]	--	--	--	--	--	--	--	--	--
Efficiency	[%]	*10				88				
Torsional Rigidity	[Nm/arc-min]	*11				3				
Maximum Torsional Backlash	[arc-min]	--				$\leq 7$				
Noise Level	dB [A]	*12				$\leq 80$				
Protection Class	--	*13				IP54 (IP65)				
Ambient Temperature	[°C]	--				0-40				
Permitted Housing Temperature	[°C]	--				90				
Weight	[kg]	*14				1.8				

## EVS o60 3-Stage Specifications

Frame Size	060								
Ratio	Unit	Note	45	50	60	70	80	90	100
Nominal Output Torque	[Nm]	*1	19	28	28	28	28	19	19
Maximum Acceleration Torque	[Nm]	*2	38	54	54	54	54	38	38
Maximum Torque	[Nm]	*3	38	54	54	54	54	38	38
Emergency Stop Torque	[Nm]	*4	65	90	90	90	90	65	65
Nominal Input Speed	[rpm]	*5				3800			
Maximum Input Speed	[rpm]	*6				6000			
No Load Running Torque	[Nm]	*7				0.2			
Maximum Radial Load	[N]	*8				3000			
Maximum Axial Load	[N]	*9				2700			
Moment of Inertia ( $\leq \emptyset 8$ )	[kgcm <sup>2</sup> ]	--	0.070	0.061	0.061	0.061	0.061	0.061	0.061
Moment of Inertia ( $\leq \emptyset 14$ )	[kgcm <sup>2</sup> ]	--	0.115	0.106	0.106	0.106	0.105	0.105	0.105
Moment of Inertia ( $\leq \emptyset 19$ )	[kgcm <sup>2</sup> ]	--	--	--	--	--	--	--	--
Efficiency	[%]	*10				88			
Torsional Rigidity	[Nm/arc-min]	*11				3			
Maximum Torsional Backlash	[arc-min]	--				$\leq 7$			
Noise Level	dB [A]	*12				$\leq 80$			
Protection Class	--	*13				IP54 (IP65)			
Ambient Temperature	[°C]	--				0-40			
Permitted Housing Temperature	[°C]	--				90			
Weight	[kg]	*14				1.8			

\*1) At nominal input speed, service life is 20,000 hours

\*2) The maximum torque when starting or stopping operation. Apply Cycle Factor  $f_0$ , found on page 468, for higher duty cycle applications

\*3) Permitted 10,000 times during service life. Based on 10% of maximum radial load and smooth output shaft

\*4) The maximum torque allowed under a stress situation. Permitted 1,000 times during service life

\*5) The average input speed at nominal input torque. Maintain housing temperature below permitted value

\*6) The maximum intermittent input speed

\*7) Torque at no load applied to the input shaft at nominal input speed

\*8) The maximum radial load that the gearbox can accept

\*9) The maximum axial load that the gearbox can accept

\*10) The efficiency at the nominal output torque rating

\*11) This does not include lost motion

\*12) Contact Nidec Drive Technology for the testing conditions and environment

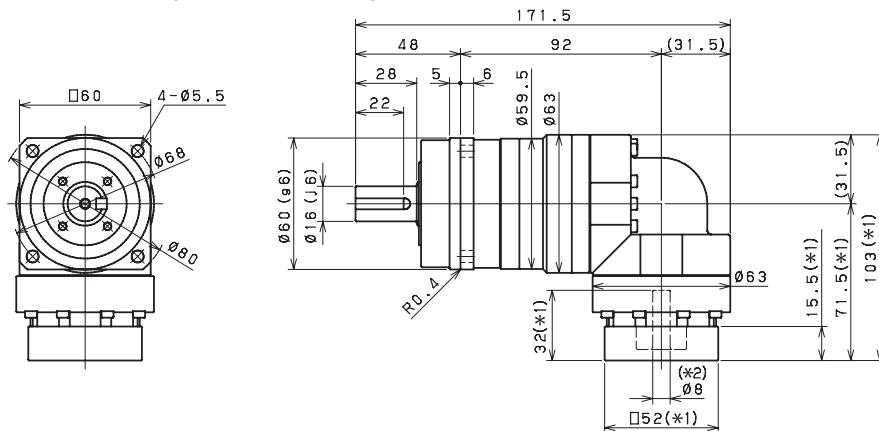
\*13) Various wash-down options are available. Contact Nidec Drive Technology for more details

\*14) Weight may vary slightly between models

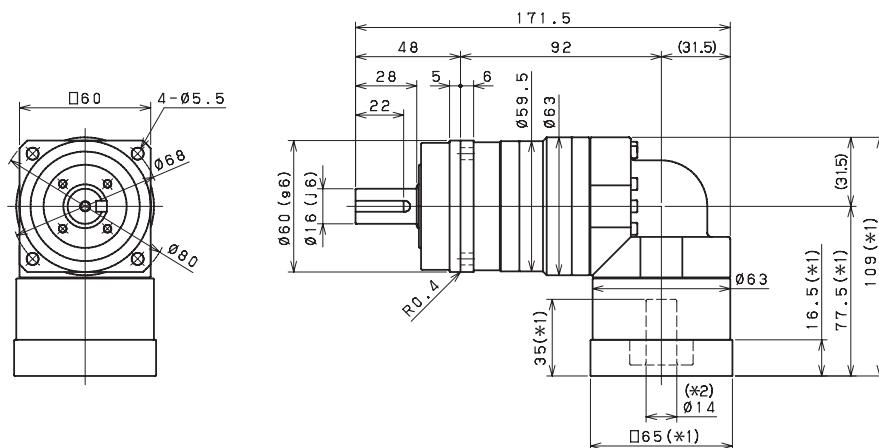
# EVS SERIES Right-angle Planetary

## EVS 060 2-Stage Dimensions

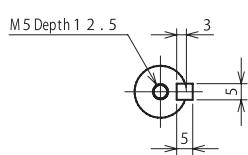
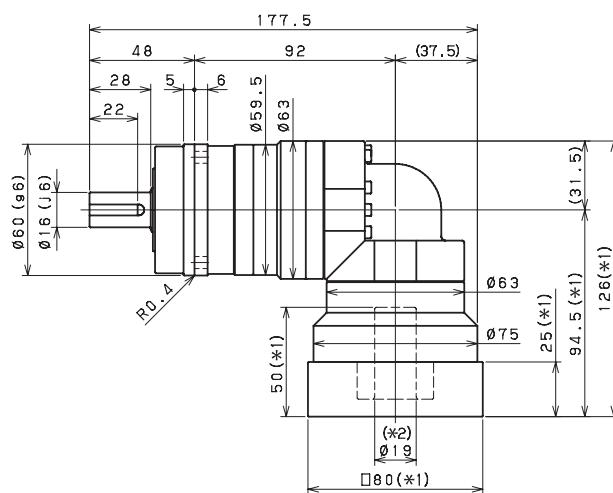
Input bore size  $\leq \varnothing 8\text{ mm}$



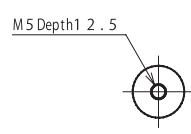
Input bore size  $\leq \varnothing 14\text{ mm}$



Input bore size  $\leq \varnothing 19\text{ mm}$



Keyed shaft



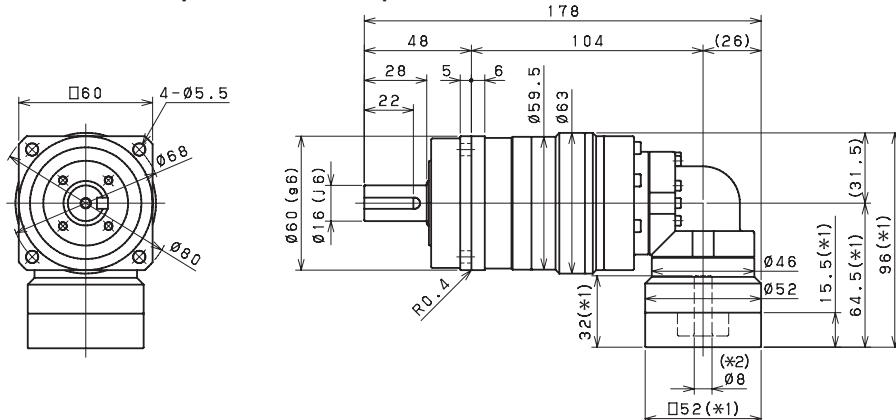
Smooth shaft

\*1) Length will vary depending on motor

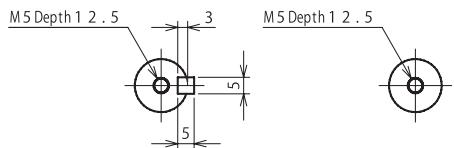
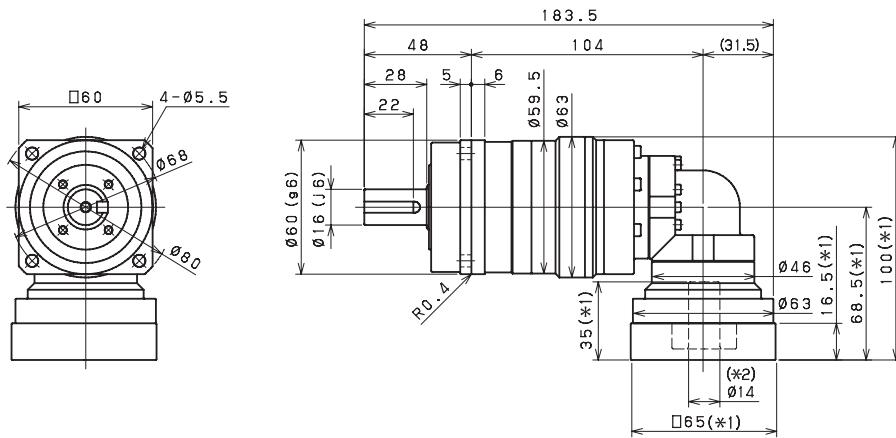
\*2) Bushing will be inserted to adapt to motor shaft

## EVS o60 3-Stage Dimensions

Input bore size  $\leq \varnothing 8\text{ mm}$



Input bore size  $\leq \varnothing 14\text{ mm}$



Keyed shaft

Smooth shaft

\*1) Length will vary depending on motor

\*2) Bushing will be inserted to adapt to motor shaft