

# EVL SERIES Right-angle Planetary

## EVL 120 2-Stage Specifications

Frame Size	120									
Ratio	Unit	Note	3	4	5	6	7	8	9	10
Nominal Output Torque	[Nm]	*1	77	108	123	154	154	154	128	128
Maximum Acceleration Torque	[Nm]	*2	172	227	272	340	340	340	240	240
Maximum Torque	[Nm]	*3	205	271	325	401	401	401	288	288
Emergency Stop Torque	[Nm]	*4	320	430	500	550	550	550	450	450
Nominal Input Speed	[rpm]	*5	3000							
Maximum Input Speed	[rpm]	*6	6000							
No Load Running Torque	[Nm]	*7	1.88							
Maximum Radial Load	[N]	*8	4300							
Maximum Axial Load	[N]	*9	3900							
Moment of Inertia ( $\leq \varnothing 14$ )	[kgcm <sup>2</sup> ]	--	--	--	--	--	--	--	--	--
Moment of Inertia ( $\leq \varnothing 19$ )	[kgcm <sup>2</sup> ]	--	6.74	5.49	5.02	4.77	4.65	4.55	4.49	4.46
Moment of Inertia ( $\leq \varnothing 28$ )	[kgcm <sup>2</sup> ]	--	8.34	7.08	6.61	6.36	6.24	6.14	6.08	6.05
Moment of Inertia ( $\leq \varnothing 38$ )	[kgcm <sup>2</sup> ]	--	15.41	14.15	13.69	13.43	13.31	13.22	13.16	13.12
Efficiency	[%]	*10	93							
Torsional Rigidity	[Nm/arc-min]	*11	31							
Maximum Torsional Backlash	[arc-min]	--	$\leq 6$							
Noise Level	dB [A]	*12	$\leq 85$							
Protection Class	--	*13	IP54 (IP65)							
Ambient Temperature	[°C]	--	0-40							
Permitted Housing Temperature	[°C]	--	90							
Weight	[kg]	*14	10.2							

## EVL 120 3-Stage Specifications

Frame Size	120									
Ratio	Unit	Note	15	16	20	25	28	30	35	40
Nominal Output Torque	[Nm]	*1	125	136	162	174	174	132	174	172
Maximum Acceleration Torque	[Nm]	*2	229	295	340	340	340	229	340	340
Maximum Torque	[Nm]	*3	229	295	340	340	340	229	340	340
Emergency Stop Torque	[Nm]	*4	450	550	550	550	550	450	550	550
Nominal Input Speed	[rpm]	*5	3100							
Maximum Input Speed	[rpm]	*6	6000							
No Load Running Torque	[Nm]	*7	1.11							
Maximum Radial Load	[N]	*8	4300							
Maximum Axial Load	[N]	*9	3900							
Moment of Inertia ( $\leq \varnothing 14$ )	[kgcm <sup>2</sup> ]	--	2.25	2.46	2.20	2.18	2.40	1.87	2.16	1.86
Moment of Inertia ( $\leq \varnothing 19$ )	[kgcm <sup>2</sup> ]	--	2.58	2.79	2.53	2.51	2.73	2.20	2.49	2.19
Moment of Inertia ( $\leq \varnothing 28$ )	[kgcm <sup>2</sup> ]	--	4.70	4.91	4.65	4.64	4.86	4.33	4.62	4.32
Moment of Inertia ( $\leq \varnothing 38$ )	[kgcm <sup>2</sup> ]	--	--	--	--	--	--	--	--	--
Efficiency	[%]	*10	88							
Torsional Rigidity	[Nm/arc-min]	*11	31							
Maximum Torsional Backlash	[arc-min]	--	$\leq 9$							
Noise Level	dB [A]	*12	$\leq 85$							
Protection Class	--	*13	IP54 (IP65)							
Ambient Temperature	[°C]	--	0-40							
Permitted Housing Temperature	[°C]	--	90							
Weight	[kg]	*14	10							

## EVL 120 3-Stage Specifications

Frame Size	120										
Ratio	Unit	Note	45	50	60	70	80	90	100		
Nominal Output Torque	[Nm]	*1	132	174	174	174	174	132	132		
Maximum Acceleration Torque	[Nm]	*2	240	340	340	340	340	240	240		
Maximum Torque	[Nm]	*3	240	340	340	340	340	240	240		
Emergency Stop Torque	[Nm]	*4	450	550	550	550	550	450	450		
Nominal Input Speed	[rpm]	*5	3100								
Maximum Input Speed	[rpm]	*6	6000								
No Load Running Torque	[Nm]	*7	1.11								
Maximum Radial Load	[N]	*8	4300								
Maximum Axial Load	[N]	*9	3900								
Moment of Inertia ( $\leq \varnothing 14$ )	[kgcm <sup>2</sup> ]	--	2.15	1.86	1.85	1.85	1.85	1.85	1.85		
Moment of Inertia ( $\leq \varnothing 19$ )	[kgcm <sup>2</sup> ]	--	2.48	2.19	2.18	2.18	2.18	2.18	2.18		
Moment of Inertia ( $\leq \varnothing 28$ )	[kgcm <sup>2</sup> ]	--	4.61	4.31	4.31	4.31	4.31	4.31	4.31		
Moment of Inertia ( $\leq \varnothing 38$ )	[kgcm <sup>2</sup> ]	--	--	--	--	--	----	--	--		
Efficiency	[%]	*10	88								
Torsional Rigidity	[Nm/arc-min]	*11	31								
Maximum Torsional Backlash	[arc-min]	--	$\leq 9$								
Noise Level	dB [A]	*12	$\leq 85$								
Protection Class	--	*13	IP54 (IP65)								
Ambient Temperature	[°C]	--	0-40								
Permitted Housing Temperature	[°C]	--	90								
Weight	[kg]	*14	10								

\*1) At nominal input speed, service life is 20,000 hours

\*2) The maximum torque when starting or stopping operation. Apply Cycle Factor  $f_0$ , found on page 468, for higher duty cycle applications

\*3) Permitted 10,000 times during service life. Based on 10% of maximum radial load and smooth output shaft

\*4) The maximum torque allowed under a stress situation. Permitted 1,000 times during service life

\*5) The average input speed at nominal input torque. Maintain housing temperature below permitted value

\*6) The maximum intermittent input speed

\*7) Torque at no load applied to the input shaft at nominal input speed

\*8) The maximum radial load that the gearbox can accept

\*9) The maximum axial load that the gearbox can accept

\*10) The efficiency at the nominal output torque rating

\*11) This does not include lost motion

\*12) Contact Nidec Drive Technology for the testing conditions and environment

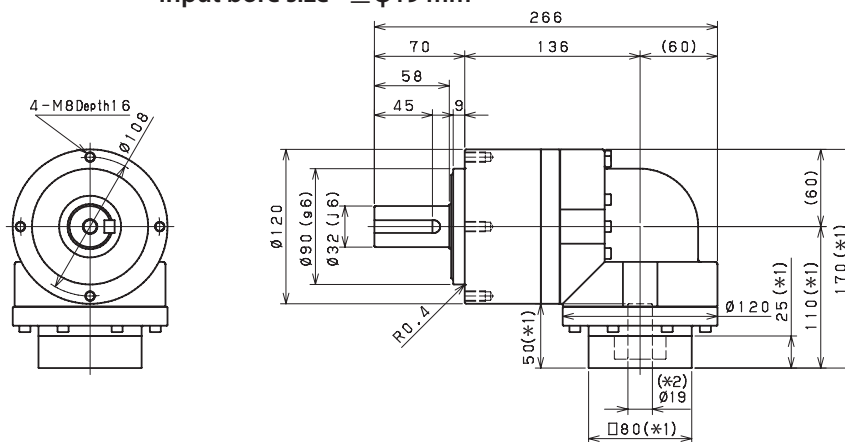
\*13) Various wash-down options are available. Contact Nidec Drive Technology for more details

\*14) Weight may vary slightly between models

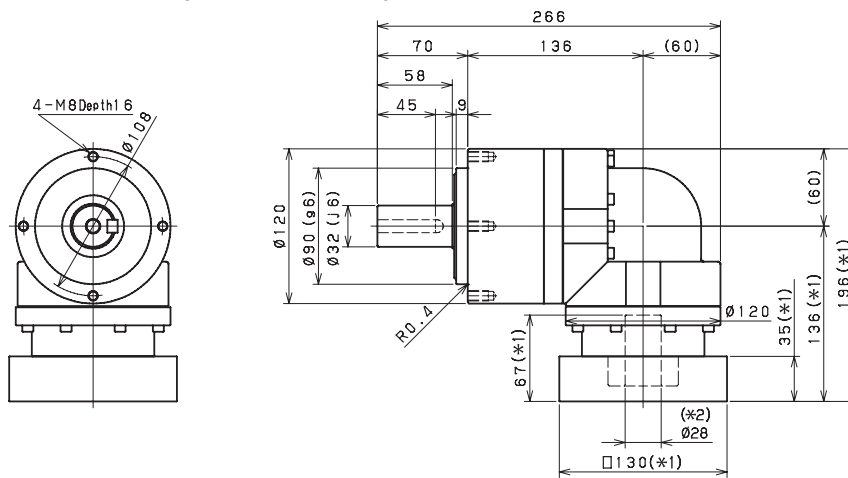
# EVL SERIES Right-angle Planetary

## EVL 120 2-Stage Dimensions

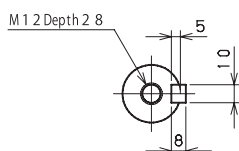
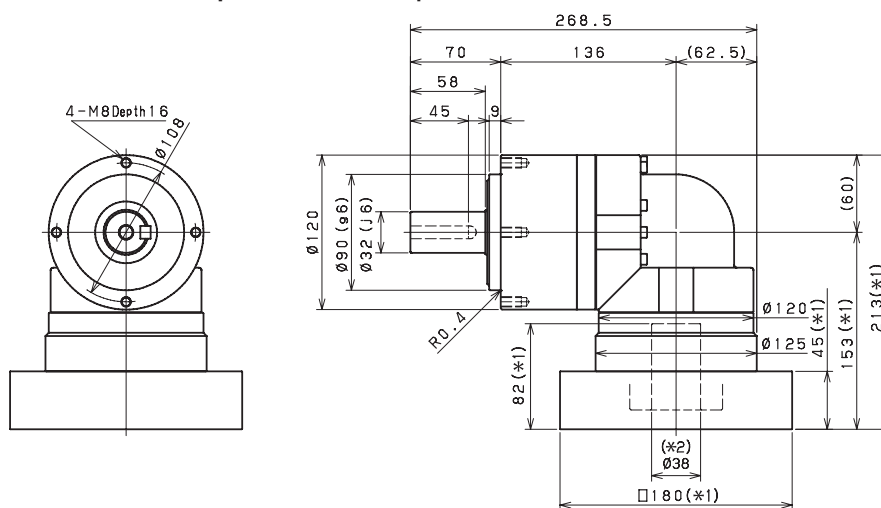
Input bore size  $\leq \phi 19$  mm



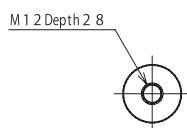
Input bore size  $\leq \phi 28$  mm



Input bore size  $\leq \phi 38$  mm



Keyed shaft



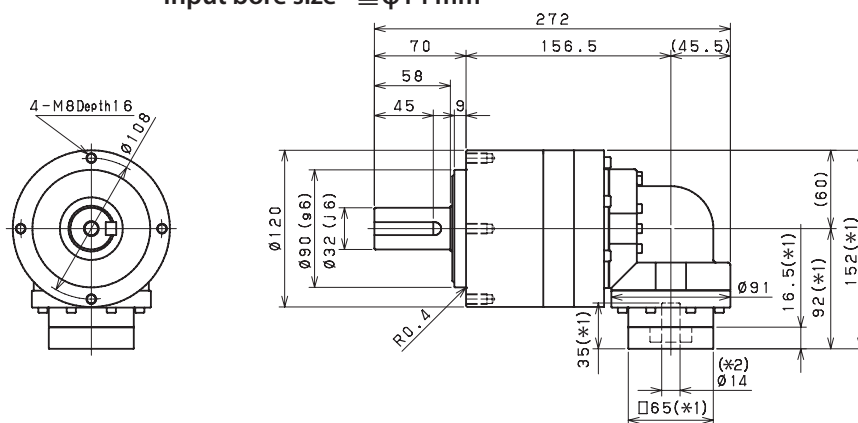
Smooth shaft

\*1) Length will vary depending on motor

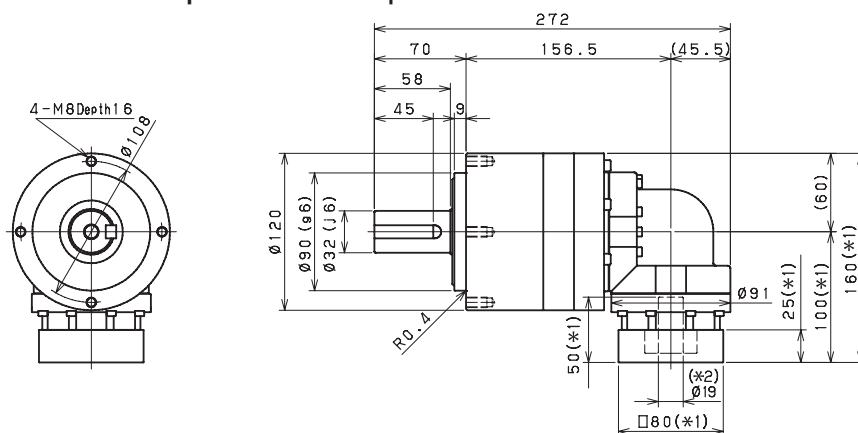
\*2) Bushing will be inserted to adapt to motor shaft

## EVL 120 3-Stage Dimensions

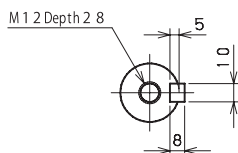
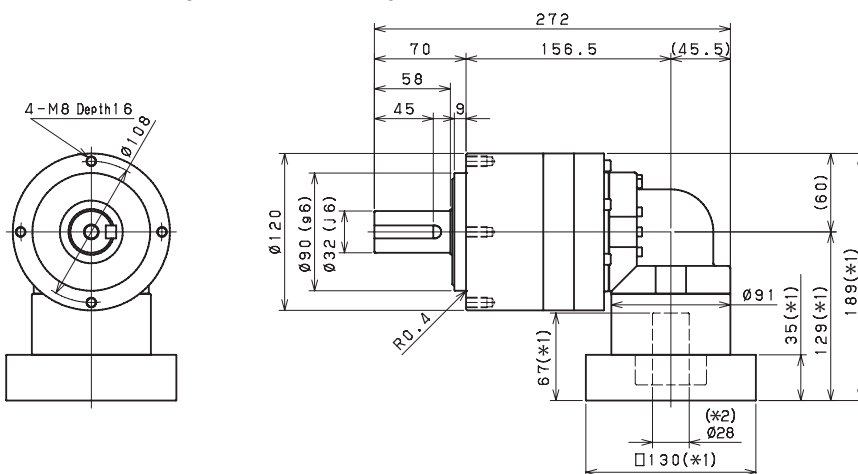
Input bore size  $\leq \phi 14$  mm



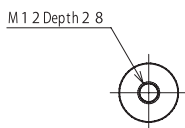
Input bore size  $\leq \phi 19$  mm



Input bore size  $\leq \phi 28$  mm



Keyed shaft



Smooth shaft

\*1) Length will vary depending on motor

\*2) Bushing will be inserted to adapt to motor shaft