

EVB SERIES Right-angle Planetary

EVB 115 2-Stage Specifications

| Frame Size | 115 | | | | | | | | | |
|---|----------------------|------|-------------|-------|-------|-------|-------|-------|-------|-------|
| Ratio | Unit | Note | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 |
| Nominal Output Torque | [Nm] | *1 | 77 | 108 | 123 | 154 | 154 | 154 | 128 | 128 |
| Maximum Acceleration Torque | [Nm] | *2 | 172 | 227 | 272 | 340 | 340 | 340 | 240 | 240 |
| Maximum Torque | [Nm] | *3 | 205 | 271 | 325 | 401 | 401 | 401 | 288 | 288 |
| Emergency Stop Torque | [Nm] | *4 | 320 | 430 | 500 | 550 | 550 | 550 | 450 | 450 |
| Nominal Input Speed | [rpm] | *5 | 3000 | | | | | | | |
| Maximum Input Speed | [rpm] | *6 | 6000 | | | | | | | |
| No Load Running Torque | [Nm] | *7 | 1.88 | | | | | | | |
| Maximum Radial Load | [N] | *8 | 4300 | | | | | | | |
| Maximum Axial Load | [N] | *9 | 3900 | | | | | | | |
| Moment of Inertia ($\leq \varnothing 14$) | [kgcm ²] | -- | -- | -- | -- | -- | -- | -- | -- | -- |
| Moment of Inertia ($\leq \varnothing 19$) | [kgcm ²] | -- | 6.74 | 5.49 | 5.02 | 4.77 | 4.65 | 4.55 | 4.49 | 4.46 |
| Moment of Inertia ($\leq \varnothing 28$) | [kgcm ²] | -- | 8.34 | 7.08 | 6.61 | 6.36 | 6.24 | 6.14 | 6.08 | 6.05 |
| Moment of Inertia ($\leq \varnothing 38$) | [kgcm ²] | -- | 15.41 | 14.15 | 13.69 | 13.43 | 13.31 | 13.22 | 13.16 | 13.12 |
| Efficiency | [%] | *10 | 93 | | | | | | | |
| Torsional Rigidity | [Nm/arc-min] | *11 | 31 | | | | | | | |
| Maximum Torsional Backlash | [arc-min] | -- | ≤ 4 | | | | | | | |
| Noise Level | dB [A] | *12 | ≤ 85 | | | | | | | |
| Protection Class | -- | *13 | IP54 (IP65) | | | | | | | |
| Ambient Temperature | [°C] | -- | 0-40 | | | | | | | |
| Permitted Housing Temperature | [°C] | -- | 90 | | | | | | | |
| Weight | [kg] | *14 | 10.4 | | | | | | | |

EVB 115 3-Stage Specifications

| Frame Size | 115 | | | | | | | | | |
|---|----------------------|------|-------------|------|------|------|------|------|------|------|
| Ratio | Unit | Note | 15 | 16 | 20 | 25 | 28 | 30 | 35 | 40 |
| Nominal Output Torque | [Nm] | *1 | 125 | 136 | 162 | 174 | 174 | 132 | 174 | 172 |
| Maximum Acceleration Torque | [Nm] | *2 | 229 | 295 | 340 | 340 | 340 | 229 | 340 | 340 |
| Maximum Torque | [Nm] | *3 | 229 | 295 | 340 | 340 | 340 | 229 | 340 | 340 |
| Emergency Stop Torque | [Nm] | *4 | 450 | 550 | 550 | 550 | 550 | 450 | 550 | 550 |
| Nominal Input Speed | [rpm] | *5 | 3100 | | | | | | | |
| Maximum Input Speed | [rpm] | *6 | 6000 | | | | | | | |
| No Load Running Torque | [Nm] | *7 | 1.11 | | | | | | | |
| Maximum Radial Load | [N] | *8 | 3900 | | | | | | | |
| Maximum Axial Load | [N] | *9 | 3900 | | | | | | | |
| Moment of Inertia ($\leq \varnothing 14$) | [kgcm ²] | -- | 2.25 | 2.46 | 2.20 | 2.18 | 2.40 | 1.87 | 2.16 | 1.86 |
| Moment of Inertia ($\leq \varnothing 19$) | [kgcm ²] | -- | 2.58 | 2.79 | 2.53 | 2.51 | 2.73 | 2.20 | 2.49 | 2.19 |
| Moment of Inertia ($\leq \varnothing 28$) | [kgcm ²] | -- | 4.70 | 4.91 | 4.65 | 4.64 | 4.86 | 4.33 | 4.62 | 4.32 |
| Moment of Inertia ($\leq \varnothing 38$) | [kgcm ²] | -- | -- | -- | -- | -- | -- | -- | -- | -- |
| Efficiency | [%] | *10 | 88 | | | | | | | |
| Torsional Rigidity | [Nm/arc-min] | *11 | 31 | | | | | | | |
| Maximum Torsional Backlash | [arc-min] | -- | ≤ 7 | | | | | | | |
| Noise Level | dB [A] | *12 | ≤ 85 | | | | | | | |
| Protection Class | -- | *13 | IP54 (IP65) | | | | | | | |
| Ambient Temperature | [°C] | -- | 0-40 | | | | | | | |
| Permitted Housing Temperature | [°C] | -- | 90 | | | | | | | |
| Weight | [kg] | *14 | 10.1 | | | | | | | |

EVB 115 3-Stage Specifications

| Frame Size | 115 | | | | | | | | | | |
|---|----------------------|------|-------------|------|------|------|------|------|------|--|--|
| Ratio | Unit | Note | 45 | 50 | 60 | 70 | 80 | 90 | 100 | | |
| Nominal Output Torque | [Nm] | *1 | 132 | 174 | 174 | 174 | 174 | 132 | 132 | | |
| Maximum Acceleration Torque | [Nm] | *2 | 240 | 340 | 340 | 340 | 340 | 240 | 240 | | |
| Maximum Torque | [Nm] | *3 | 240 | 340 | 340 | 340 | 340 | 240 | 240 | | |
| Emergency Stop Torque | [Nm] | *4 | 450 | 550 | 550 | 550 | 550 | 450 | 450 | | |
| Nominal Input Speed | [rpm] | *5 | 3100 | | | | | | | | |
| Maximum Input Speed | [rpm] | *6 | 6000 | | | | | | | | |
| No Load Running Torque | [Nm] | *7 | 1.11 | | | | | | | | |
| Maximum Radial Load | [N] | *8 | 4300 | | | | | | | | |
| Maximum Axial Load | [N] | *9 | 3900 | | | | | | | | |
| Moment of Inertia ($\leq \varnothing 14$) | [kgcm ²] | -- | 2.15 | 1.86 | 1.85 | 1.85 | 1.85 | 1.85 | 1.85 | | |
| Moment of Inertia ($\leq \varnothing 19$) | [kgcm ²] | -- | 2.48 | 2.19 | 2.18 | 2.18 | 2.18 | 2.18 | 2.18 | | |
| Moment of Inertia ($\leq \varnothing 28$) | [kgcm ²] | -- | 4.61 | 4.31 | 4.31 | 4.31 | 4.31 | 4.31 | 4.31 | | |
| Moment of Inertia ($\leq \varnothing 38$) | [kgcm ²] | -- | -- | -- | -- | -- | -- | -- | -- | | |
| Efficiency | [%] | *10 | 88 | | | | | | | | |
| Torsional Rigidity | [Nm/arc-min] | *11 | 31 | | | | | | | | |
| Maximum Torsional Backlash | [arc-min] | -- | ≤ 7 | | | | | | | | |
| Noise Level | dB [A] | *12 | ≤ 85 | | | | | | | | |
| Protection Class | -- | *13 | IP54 (IP65) | | | | | | | | |
| Ambient Temperature | [°C] | -- | 0-40 | | | | | | | | |
| Permitted Housing Temperature | [°C] | -- | 90 | | | | | | | | |
| Weight | [kg] | *14 | 10.1 | | | | | | | | |

*1) At nominal input speed, service life is 20,000 hours

*2) The maximum torque when starting or stopping operation. Apply Cycle Factor f_0 , found on page 468, for higher duty cycle applications

*3) Permitted 10,000 times during service life. Based on 10% of maximum radial load and smooth output shaft

*4) The maximum torque allowed under a stress situation. Permitted 1,000 times during service life

*5) The average input speed at nominal input torque. Maintain housing temperature below permitted value

*6) The maximum intermittent input speed

*7) Torque at no load applied to the input shaft at nominal input speed

*8) The maximum radial load that the gearbox can accept

*9) The maximum axial load that the gearbox can accept

*10) The efficiency at the nominal output torque rating

*11) This does not include lost motion

*12) Contact Nidec Drive Technology for the testing conditions and environment

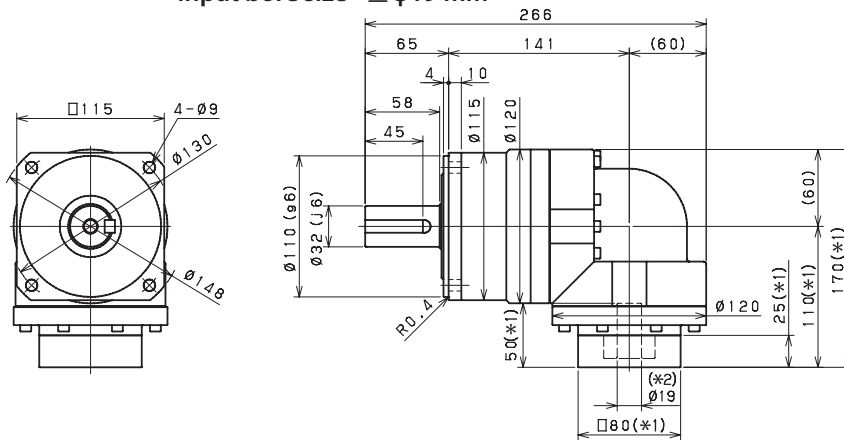
*13) Various wash-down options are available. Contact Nidec Drive Technology for more details

*14) Weight may vary slightly between models

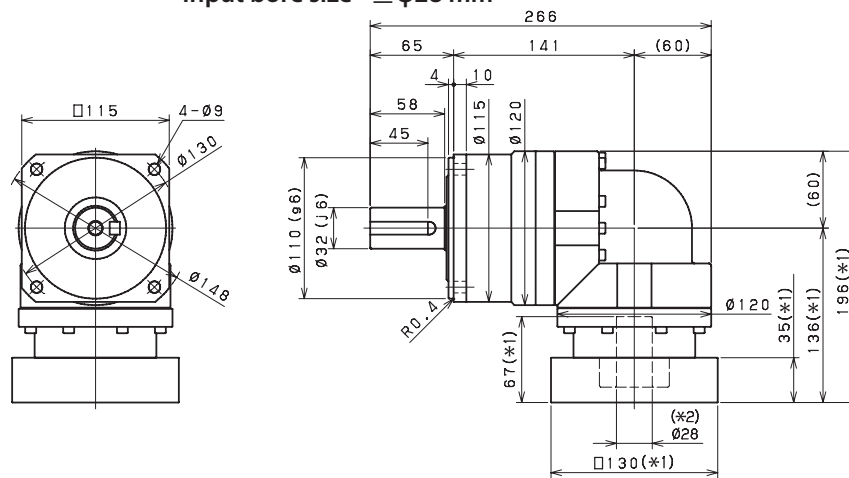
EVB SERIES Right-angle Planetary

EVB 115 2-Stage Dimensions

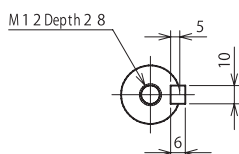
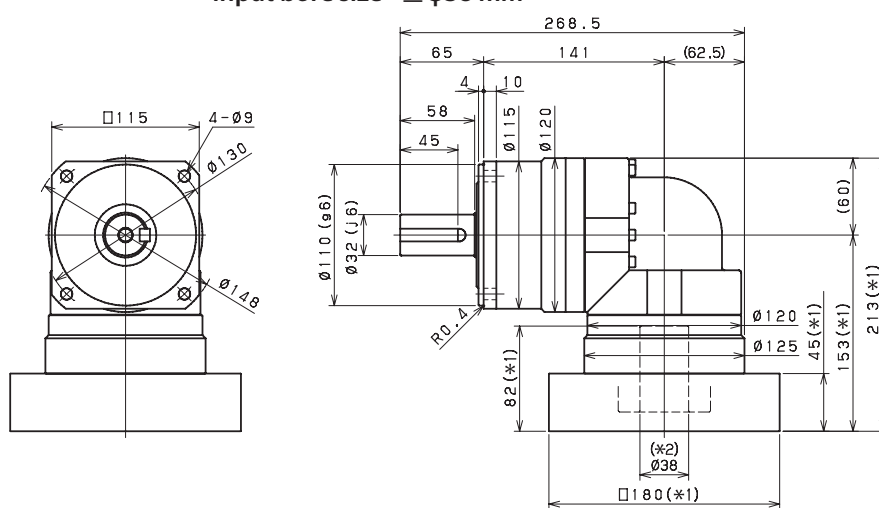
Input bore size $\leq \phi 19$ mm



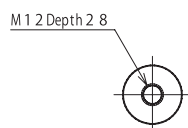
Input bore size $\leq \phi 28$ mm



Input bore size $\leq \phi 38$ mm



Keyed shaft

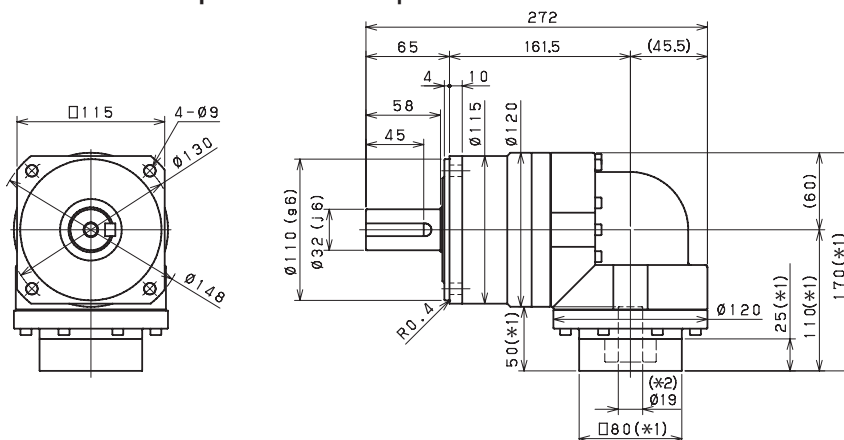


Smooth shaft

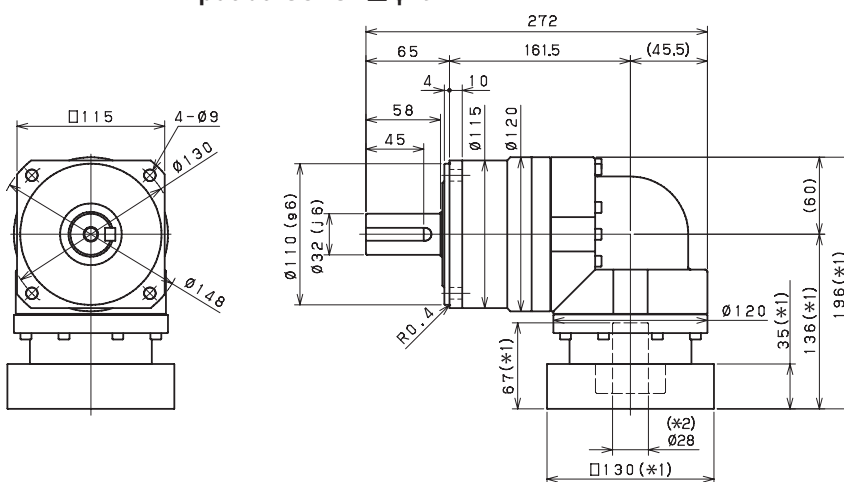
- *1) Length will vary depending on motor
- *2) Bushing will be inserted to adapt to motor shaft

EVB 115 3-Stage Dimensions

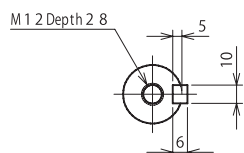
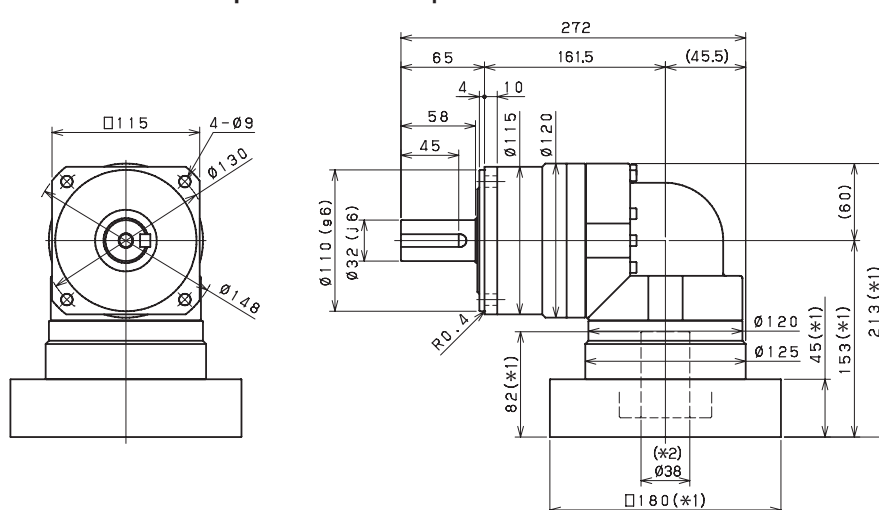
Input bore size $\leq \phi 14$ mm



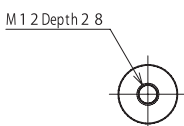
Input bore size $\leq \phi 19$ mm



Input bore size $\leq \phi 28$ mm



Keyed shaft



Smooth shaft

*1) Length will vary depending on motor

*2) Bushing will be inserted to adapt to motor shaft